

Linear Temporal Logics

Describe LT Properties by LTL

Motivations

- It is not practical to write down $P \subseteq (2^{AP})^\omega$ directly
- Propositional and predicate logics are “static”
- How to express temporal properties in a structured, user-friendly and rigorous manner

Approach

- Use **linear temporal logics (LTL)**
- Introduce temporal operators in addition to Boolean operators

LTL Syntax

A (propositional) **Linear Temporal Logic (LTL)** formula ϕ over a given set of atomic propositions AP is recursively defined as

$$\phi ::= \text{TRUE} \mid a \mid \phi_1 \wedge \phi_2 \mid \neg\phi \mid \bigcirc\phi \mid \phi_1 U \phi_2$$

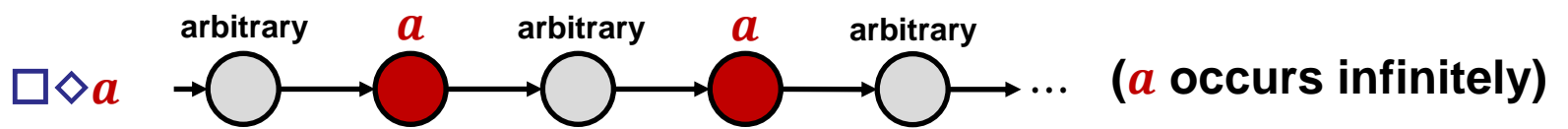
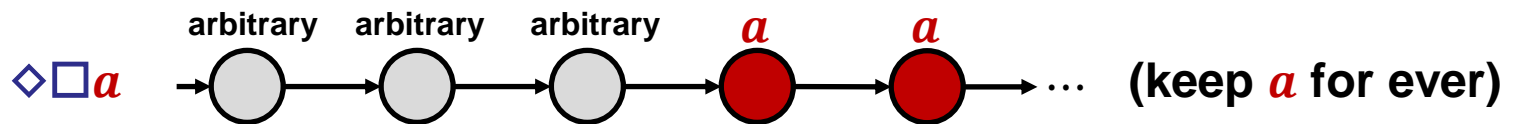
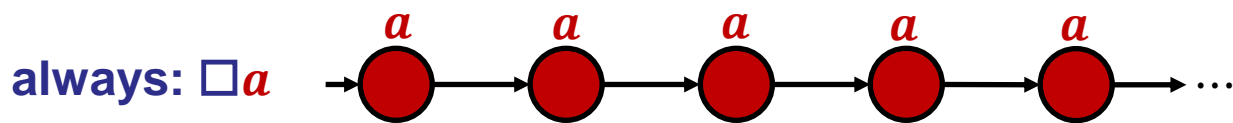
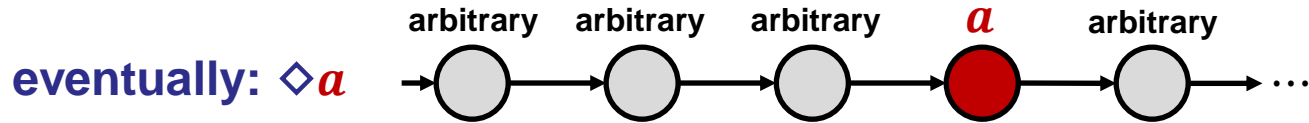
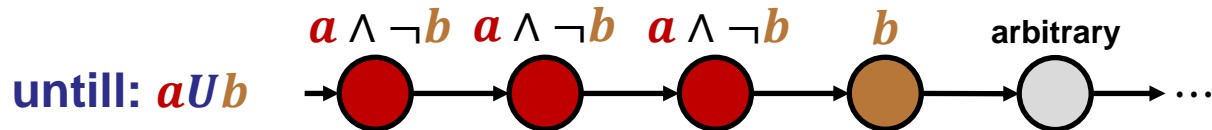
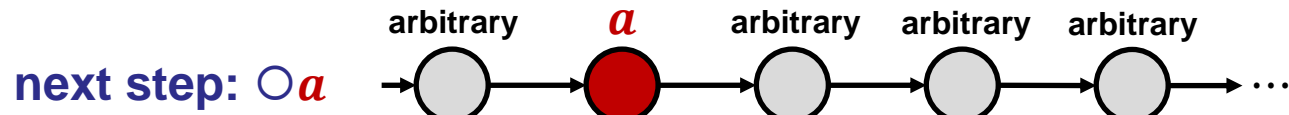
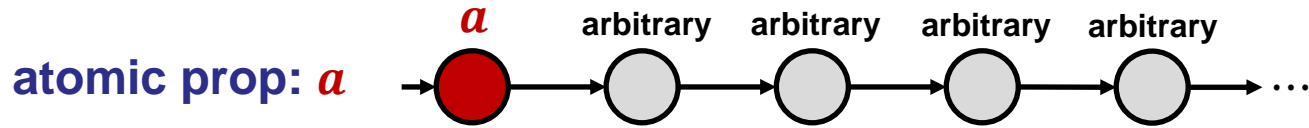
where a is an atomic proposition and ϕ, ϕ_1 and ϕ_2 are LTL formulas.

- Formula $\bigcirc\phi$ holds at the current moment, if ϕ holds in the **next** “step”
- Formula $\phi_1 U \phi_2$ holds at the current moment, if there is some future moment for which ϕ_2 holds and ϕ_1 holds at all moments **until** that future moment.

We can also define the following operators

- Boolean oper.: “**or**” $\phi_1 \vee \phi_2 := \neg(\neg\phi_1 \wedge \neg\phi_2)$, “**implies**” $\phi_1 \rightarrow \phi_2 := \neg\phi_1 \vee \phi_2$
- Temporal oper.: “**eventually**” $\diamond\phi := \text{TRUE} U \phi$, “**always**” $\square\phi := \neg\diamond\neg\phi$

LTL Semantics: Informal



LTL Semantics: Formal

- LTL formulas are used to **evaluate infinite words over 2^{AP}**
- Let $\sigma = A_0A_1A_2 \dots \in (2^{AP})^\omega$, define $\sigma[j \dots] = A_jA_{j+1}A_{j+2} \dots$
- Infinite word σ satisfies formula ϕ , denoted by $\sigma \models \phi$, is defined by

- $\sigma \models \text{True}$
- $\sigma \models a$ iff $a \in A_0$ (i.e., $A_0 \models a$)
- $\sigma \models \phi_1 \wedge \phi_2$ iff $\sigma \models \phi_1$ and $\sigma \models \phi_2$
- $\sigma \models \neg\phi$ iff $\sigma \not\models \phi$
- $\sigma \models \bigcirc\phi$ iff $\sigma[1 \dots] = A_1A_2A_3 \dots \models \phi$
- $\sigma \models \phi_1 U \phi_2$ iff $\exists j \geq 0: \sigma[j \dots] \models \phi_2$ and $\forall 0 \leq i < j: \sigma[i \dots] \models \phi_1$

- The set of all words satisfying ϕ is $\text{Word}(\phi) = \{\sigma \in (2^{AP})^\omega : \sigma \models \phi\}$, i.e., $\sigma \models \phi$ iff $\sigma \in \text{Word}(\phi)$

LTL Example: Mutual Exclusion

- The **safety** property stating that P_1 and P_2 never simultaneously have access to their critical sections

$$\Box(\neg crit_1 \vee \neg crit_2)$$

- The **liveness** requirement stating that each process P_i is infinitely often in its critical section

$$(\Box\Diamond crit_1) \wedge (\Box\Diamond crit_2)$$

- The **strong fairness** requirement stating that infinitely waiting process will eventually enter its critical section infinitely often:

$$(\Box\Diamond wait_1 \rightarrow \Box\Diamond crit_1) \wedge (\Box\Diamond wait_2 \rightarrow \Box\Diamond crit_2)$$

LTL Example: Traffic Light

- The traffic light is infinitely often green

$$\Box \Diamond green$$

- Once red, the light cannot become green immediately

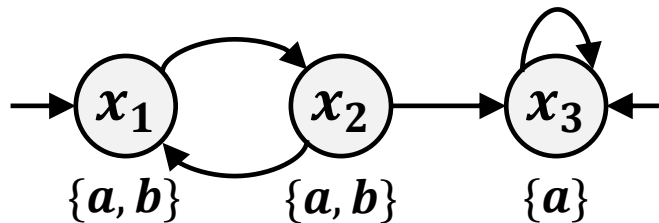
$$\Box (red \rightarrow \neg \bigcirc green)$$

- Once red, the light always becomes green eventually after being yellow for some time

$$\Box (red \rightarrow \bigcirc (red \ U (yellow \wedge \bigcirc (yellow \ U green))))$$

LTL Semantics on LTSs

- LTL formula ϕ evaluates infinite words over 2^{AP}
- LTS T generates a set of infinite words (traces) from initial states
- A state $x \in X$ in T satisfies ϕ , denoted by $x \models \phi$, if all traces generated from x satisfy ϕ
- We say LTL T satisfies ϕ , denoted by $T \models \phi$, if all its initial states satisfy ϕ , i.e., $Trace(T) \subseteq Word(\phi)$

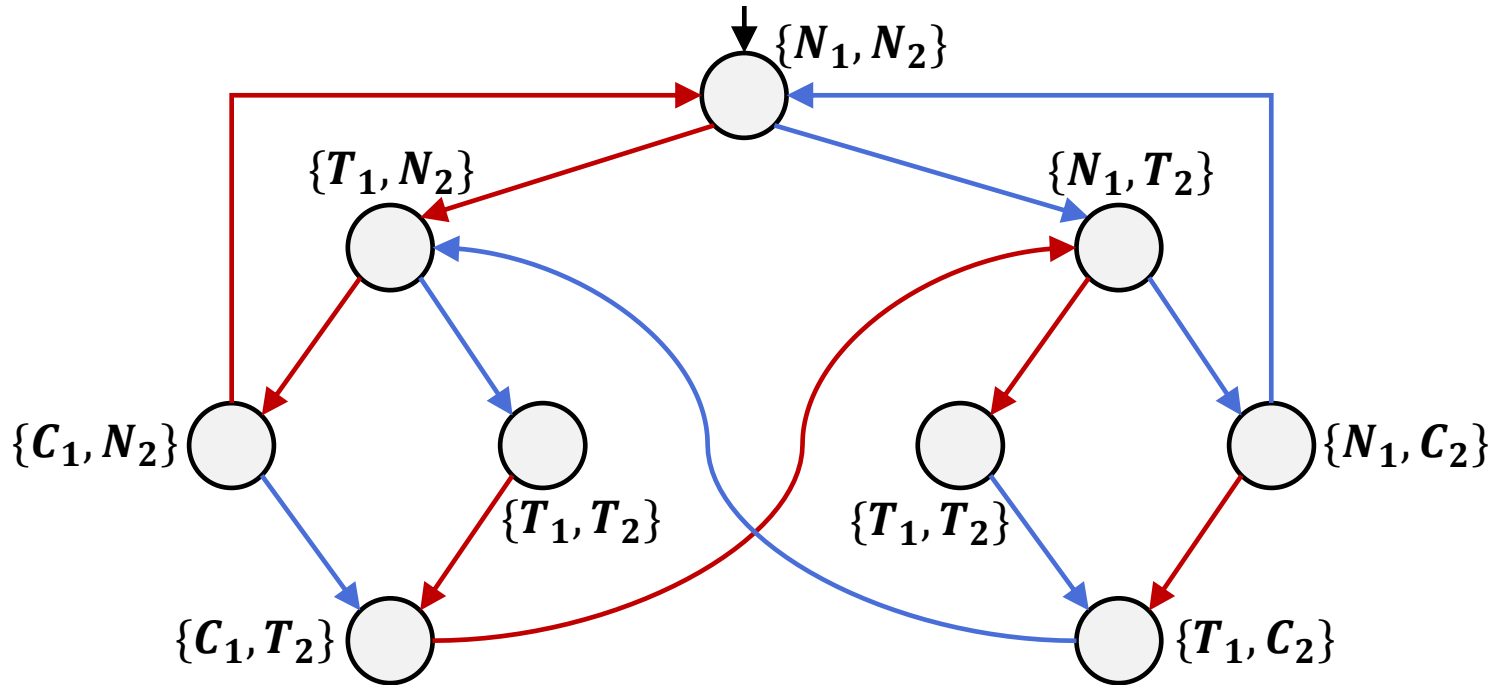


LTS T

- $T \models \Box a$
- $T \not\models \bigcirc(a \wedge b)$ since $x_1 \models \bigcirc(a \wedge b)$ but $x_3 \not\models \bigcirc(a \wedge b)$
- $T \models \Box(\neg b \rightarrow \Box(a \wedge \neg b))$
- $T \not\models b U (a \wedge \neg b)$ since $\{a, b\}^\omega \not\models b U (a \wedge \neg b)$

How to check whether $T \models \phi$ or not?

LTl Example: Mutually Exclusive Processes



- $T \models \square(T_1 \rightarrow \diamond C_1)$? **Yes!**
- $T \models \square \diamond C_1$ **No! Consider trace $(\{N_1, N_2\}\{N_1, T_2\}\{N_1, C_2\})^\omega$**
- $T \models \square \diamond T_1 \rightarrow \square \diamond C_1$? **Yes!**

Co-Safe LTL Syntax

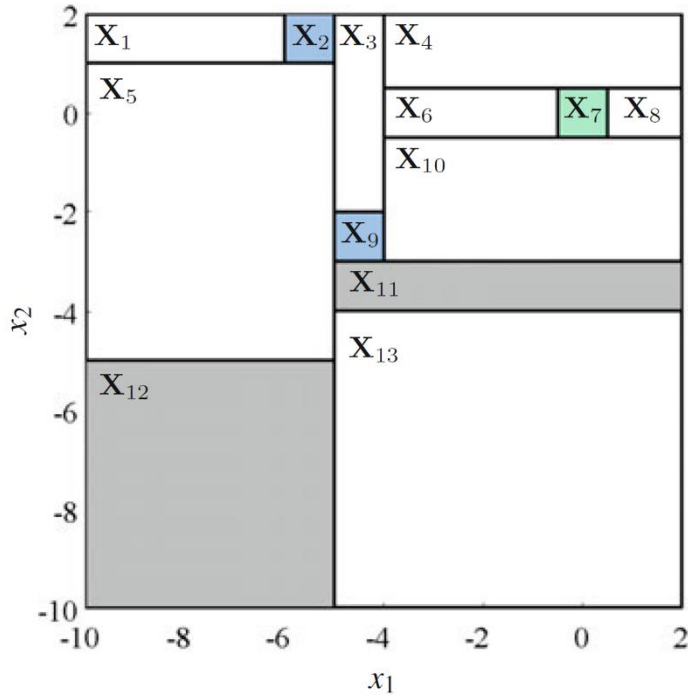
A (propositional) **Co-Safe Linear Temporal Logic (scLTL)** formula ϕ over a given set of atomic proposition AP is recursively defined as

$$\phi ::= \text{TRUE} \mid a \mid \neg a \mid \phi_1 \wedge \phi_2 \mid \phi_1 \vee \phi_2 \mid \bigcirc \phi \mid \phi_1 U \phi_2$$

where a is an atomic proposition and ϕ, ϕ_1 and ϕ_2 are LTL formulas.

- Negation can only be used for atomic propositions not a general formula
- “Always” cannot be expressed since $\Box \phi := \neg \Diamond \neg \phi$ is not well defined
- We can only use temporal operators \bigcirc, U and \Diamond
- **Any infinite word satisfying scLTL ϕ has a finite “good” prefix such that any infinite continuation of this good prefix satisfies ϕ**
- Denote $\mathcal{L}_{pref, \phi}$ as the set of finite good prefixes of scLTL formula ϕ

Example: Co-Safe LTL Syntax



Consider an agent moving in the planar environment

- Visit regions X_2 or X_9 and then the target region X_7 , while avoiding X_{11} and X_{12} , and staying inside of $X = [-10 \ 2]^2$ until the target region is reached.

$$\phi = ((\neg X_{11} \wedge \neg X_{12} \wedge \neg \mathit{Out}) U X_7) \wedge (\neg X_7 U (X_2 \vee X_9))$$

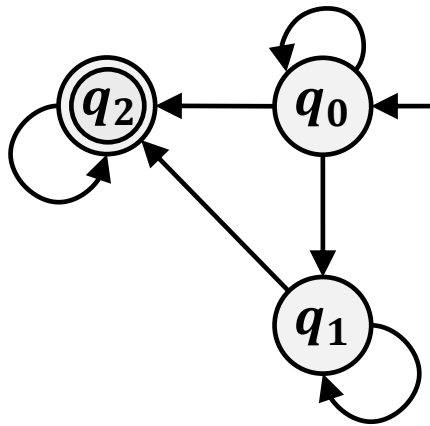
- Good prefix, e.g., $X_2X_3X_4X_7$ or $X_2X_3X_9X_3X_9X_{10}X_8X_7$
- In general, there may have infinite many finite good prefixes

Computation Tree Logic

- LTL implicitly quantifies **universally** over paths

$\langle T, x \rangle \models \phi$ iff **for every path** π starting at x , we have $\langle T, \pi \rangle \models \phi$

- Properties that assert the existences of a path cannot be expressed, e.g., always has the possibility to reach some states.



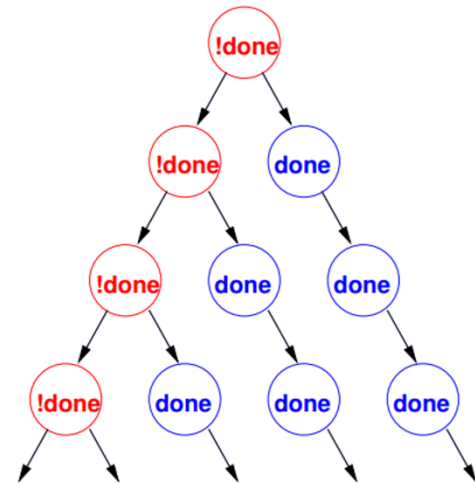
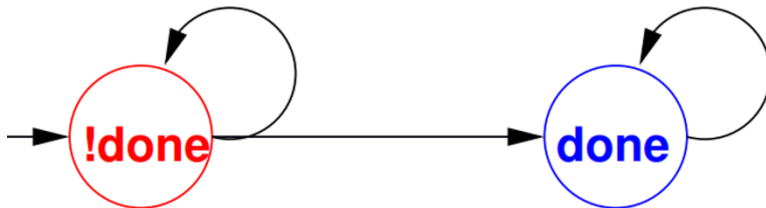
- I always have the opportunity to reach q_2
- Cannot be expressed by LTL!

Computation Tree Logic

- LTL implicitly quantifies **universally** over paths
 - $\langle T, x \rangle \models \phi$ iff **for every path** π starting at x , we have $\langle T, \pi \rangle \models \phi$
- Properties that assert the existences of a path cannot be expressed, e.g., always has the possibility to reach some states.
- The **computation tree logic (CTL)** solves this problem. The idea is to evaluate over branching-time structures (trees) with path quantifiers:
 - For All Paths: **A**
 - Exists a Path: **E**
 - Every temporal operator preceded by a path quantifier
 - Notation: $\square \rightsquigarrow$ **G** globally in the future
 - $\bigcirc \rightsquigarrow$ **X** next time
 - $\diamond \rightsquigarrow$ **F** sometime in the future

CTL Semantics: Intuitions

- **Globally:** $AG\phi$ is true iff ϕ is always true in the future
- **Necessarily Next:** $AX\phi$ is true iff ϕ is true in every successor state
- **Possibly Next:** $EX\phi$ is true iff ϕ is true in some successor state
- **Necessarily in the Future:** $AF\phi$ is true iff ϕ is inevitably true in some future time
- **Possibly in the Future:** $EF\phi$ is true iff ϕ maybe true in some future time



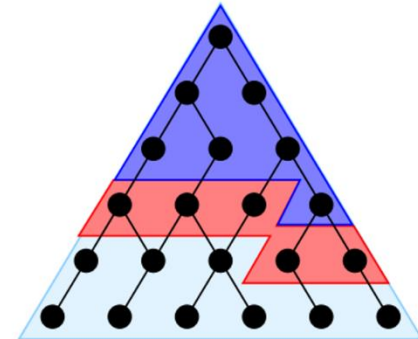
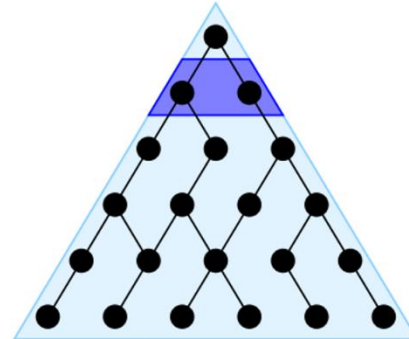
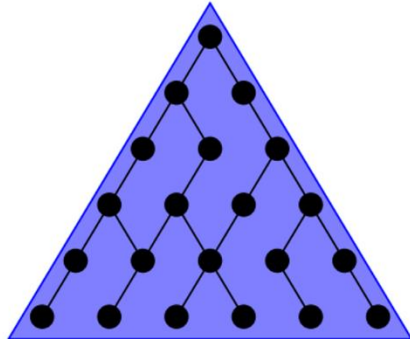
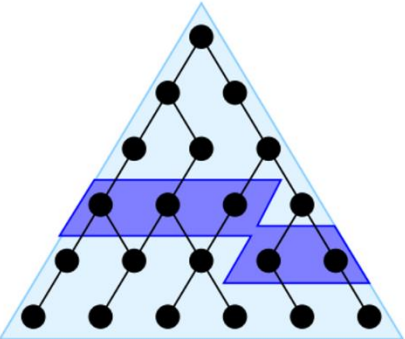
CTL Semantics: Intuitions

finally P

globally P

next P

P until q

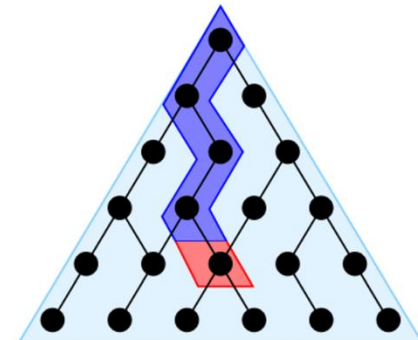
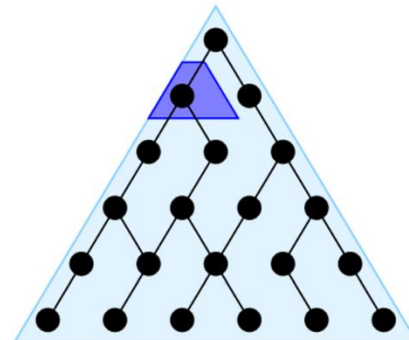
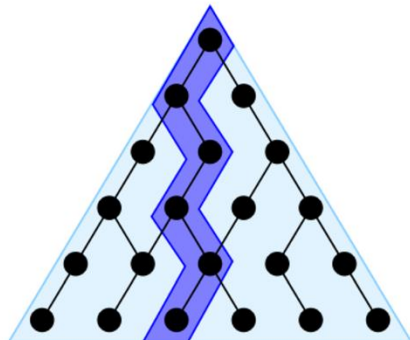
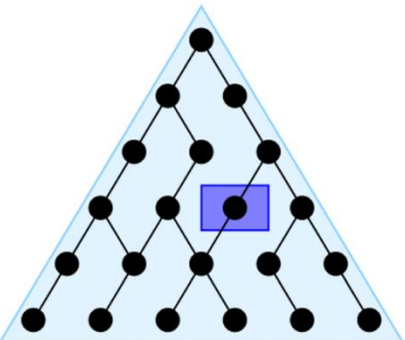


$AF P$

$AG P$

$AX P$

$A[P U q]$



$EF P$

$EG P$

$EX P$

$E[P U q]$

Stage Summary

- **LTL provides an user-friendly way for writing down LT properties**
- **LTL = Temporal operators + Boolean operators**
- **LTL formulas only evaluate infinite words**
- **Co-safe LTL can be satisfied in finite horizon**
(recall safety is something that can be violated in finite horizon)
- **LTL cannot capture branching-time properties; need CTL**
- **CTL puts quantifiers for states to capture branching-time properties**

Question

- What is $AGEF\phi$?
 - A for all paths
 - E exists a path
 - G globally in the future
 - F sometime in the future

Review of Last Lecture

- LTL = Temporal operators + Boolean operators
- LTL formulas only evaluate infinite words
- Co-safe LTL can be satisfied in finite horizon
- LTL cannot capture branching-time properties; need CTL
- CTL puts quantifiers for states to capture branching-time properties
- LTL only tells how to describe a property; it does not tell how to generate the underlying property (language) $Word(\phi) \subseteq (2^{AP})^\omega$
- We use Automata to generate languages describing good behaviors